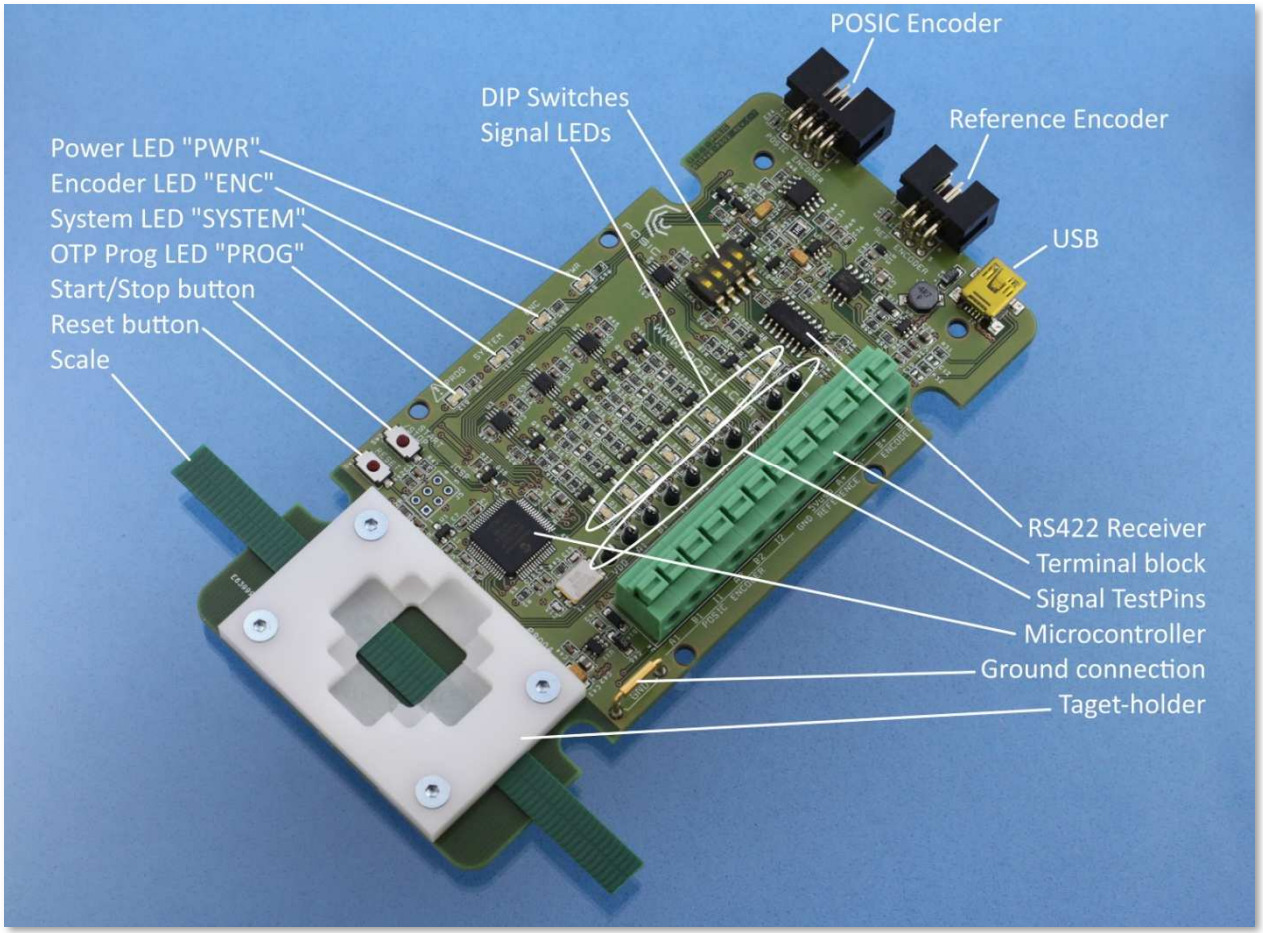
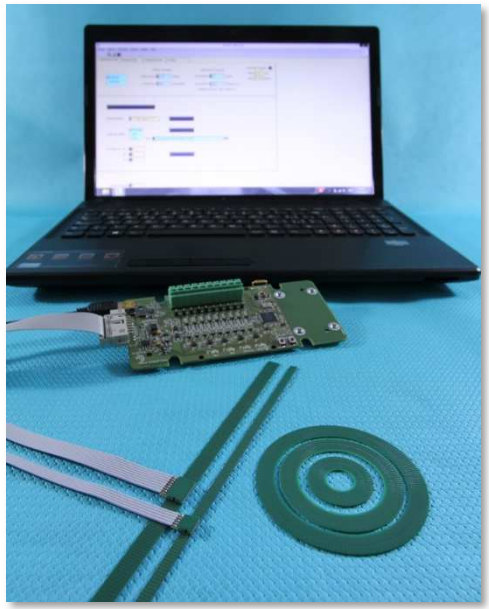
Evaluation & Programming Tool - User Guide

Interface Board

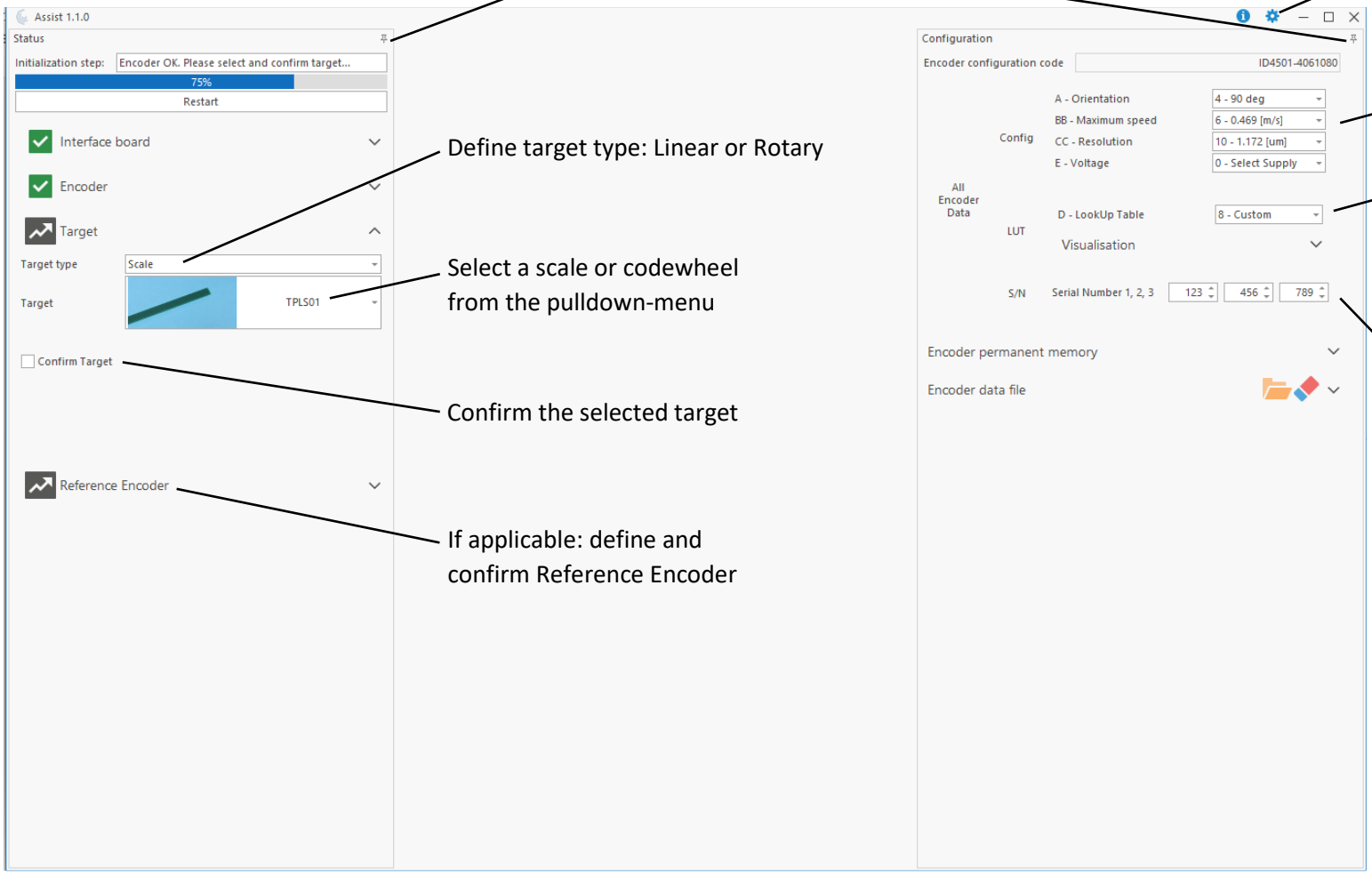




Evaluation & Programming Tool:
- ASSIST Software
- USB cable
- Interface Board
- Encoders
- Scales or codewheels

Power LED “PWR”	Active when the Interface Board is powered via the USB-cable
Encoder LED “ENC”	Active when the encoder is powered and the encoder is communicating or operating
System LED “SYSTEM”	Active when the microcontroller on the Interface Board is active
OTP Prog LED “PROG”	Active when the OTP-memory in the encoder is being programmed

ASSIST - Status and Configuration windows



Show/hide the Status and configuration windows

Check to enable/disable warning messages

Define target type: Linear or Rotary

Configure the encoder
See datasheet page 4

Select a scale or codewheel from the pulldown-menu

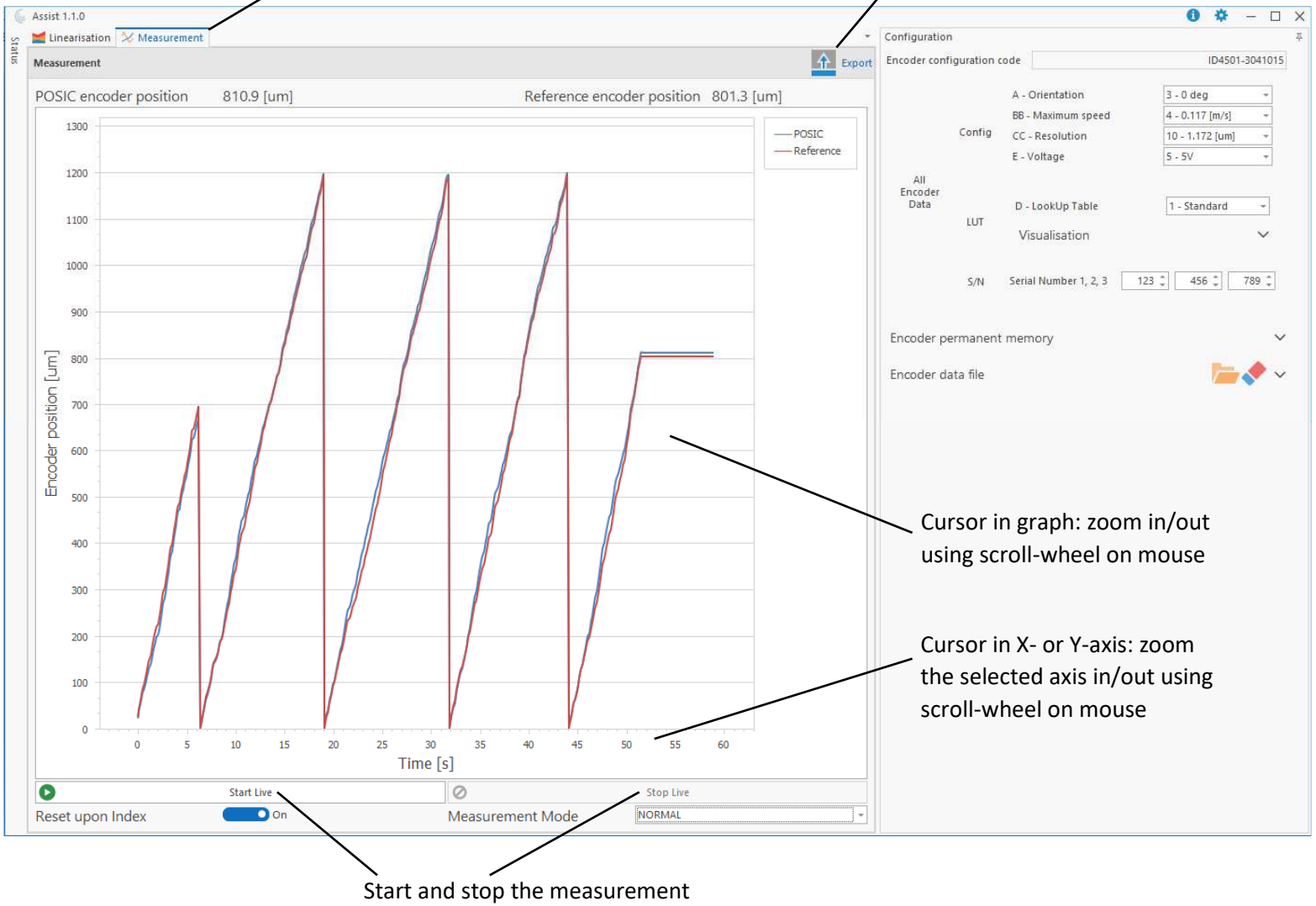
Select LookUp Table (LUT)
Recommendation for new users: Standard LUT

Confirm the selected target

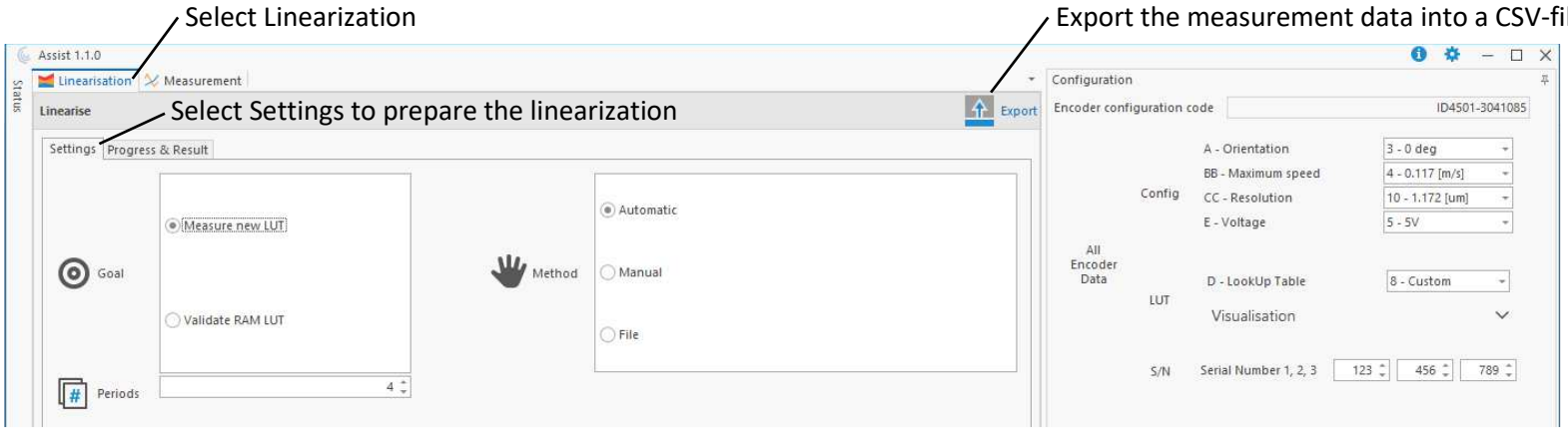
User-defined Serial Numbers

If applicable: define and confirm Reference Encoder

ASSIST - Measurement window



ASSIST - Linearization window



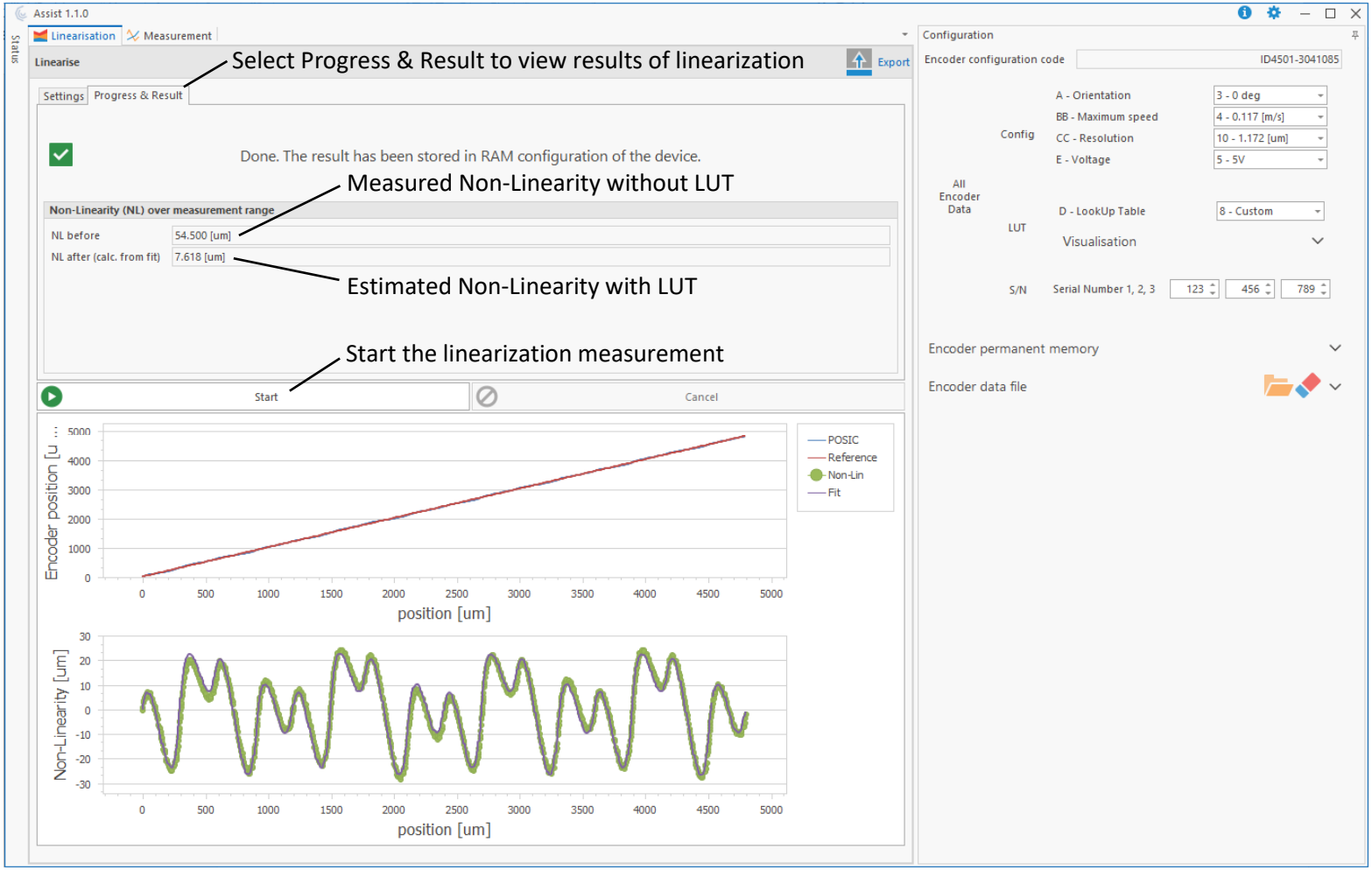
Goal	Measure new LUT:	Measure the non-linearity with LUT = 0 and calculate a custom LUT for this specific scale or codewheel
	Validate RAM LUT:	Measure the non-linearity with a specified LUT (e.g. custom LUT or Standard LUT)
Method	Automatic:	Linearization using a reference encoder
	Manual:	This method is not implemented yet
	File:	This method is not implemented yet
Periods	Number of scale/codewheel periods over which the linearization takes place. Recommendations:	
	Linear scales:	Number of periods corresponding to approximately 70% of the typical movement range
	Codewheels:	Number of periods on the codewheel

Notes:

- A reference encoder (e.g. a high-end optical encoder) must be mechanically connected to the POSIC scale/codewheel. The A/B outputs of the reference encoder must be electrically connected to the Interface Board.
- The Export-file can be read using Excel or a similar software and contains all the relevant encoder- and measurement-information.

Linearization – Measure and calculate LUT

Step 1 of the linearization procedure: measure the non-linearity without LUT and calculate a Custom LUT

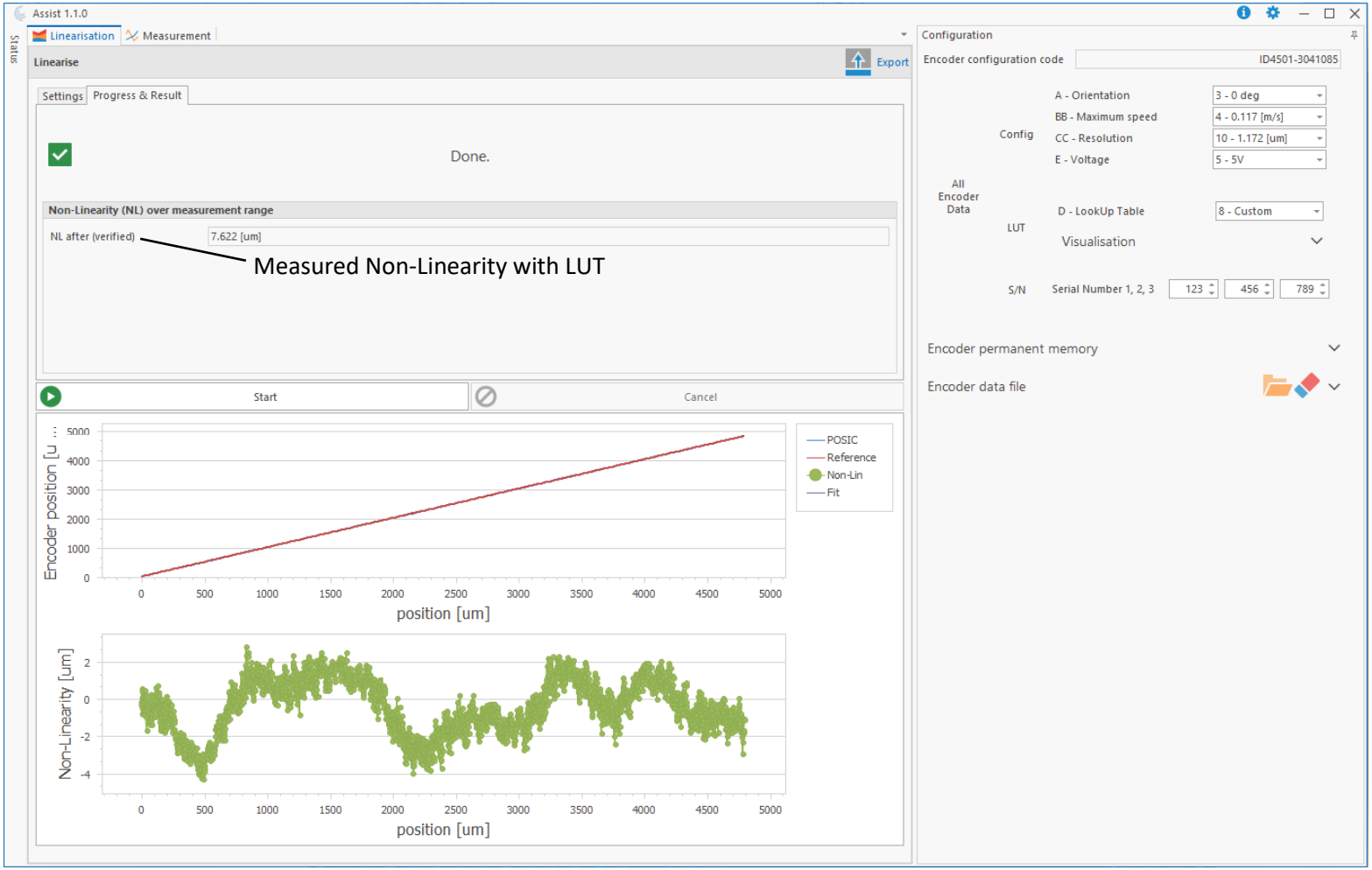


Notes:

- Keep moving in the same direction during linearization. If the direction of movement changes, the linearization measurement will be aborted.
- Keep the actual speed of movement during linearization at least 60 x lower than the value of BB - Maximum speed in the Configuration window.
- Keep the actual speed of movement during linearization as constant as reasonably possible.

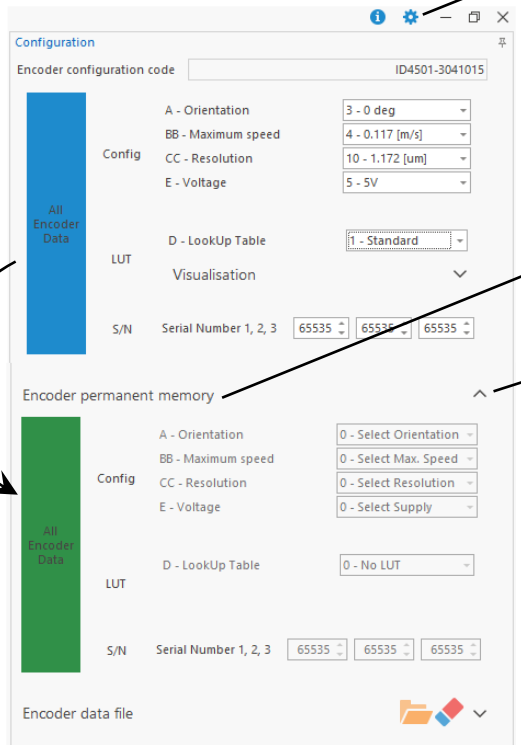
Linearization – Validation of the LUT

Step 2 of the linearization procedure: validation of the Custom LUT calculated in the preceding section.



Programming Encoder permanent memory

Check to enable/disable warnings for programming

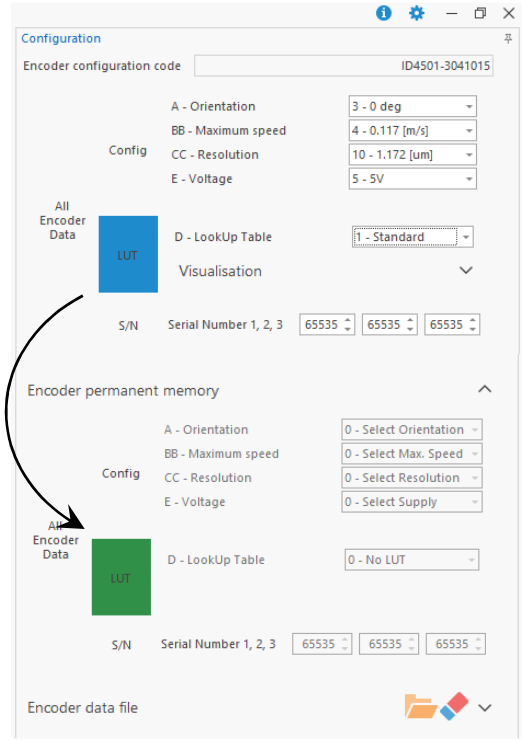


Drag & Drop from Configuration to Encoder permanent memory and vice versa:

- All Encoder Data
- Configuration
- LookUp Table LUT
- Serial Number S/N

Select Encoder Permanent memory

Pull-down menu for Config, LUT and S/N



Drag & Drop only LUT from Configuration to Encoder permanent memory

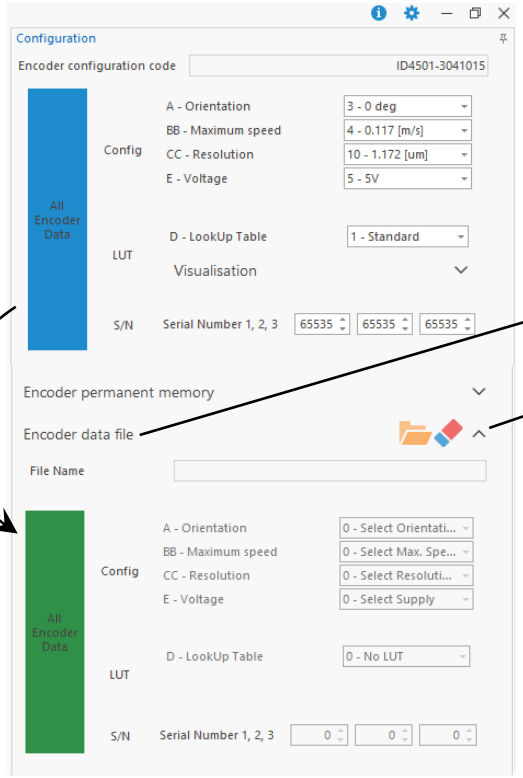
Notes:

- The encoder permanent memory (OTP = One Time Programmable) can be programmed only once, the OTP memory cannot be re-programmed
- Warning messages appear prior to OTP-programming, changing LUT etc. These warnings can be disabled in the settings menu at the right top-side of the ASSIST window

Write to and read from an Encoder data file

Drag & Drop from Configuration to Encoder data file and vice versa:

- All Encoder Data
- Configuration
- LookUp Table LUT
- Serial Number S/N

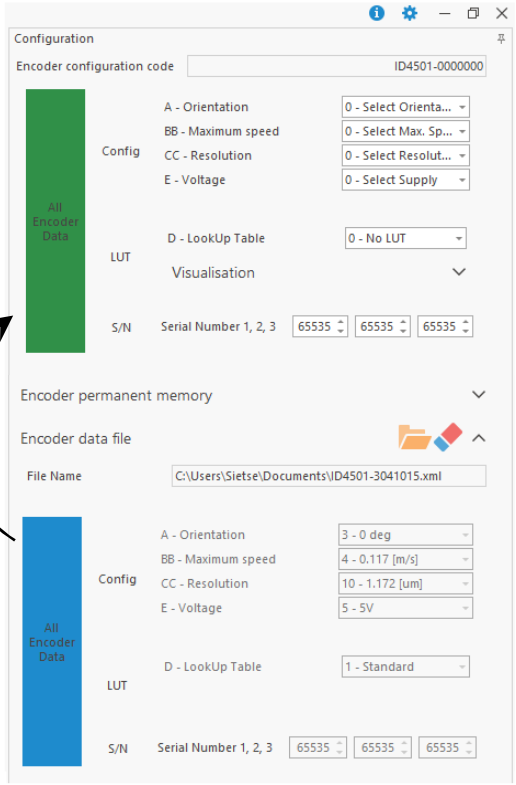


Select Encoder data file

Pull down menu for Config, LUT and S/N

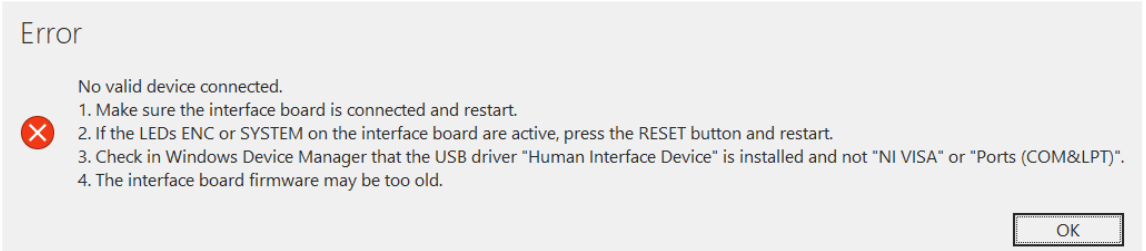
Drag & Drop from Encoder data file to Configuration:

- All Encoder Data
- Configuration
- LookUp Table LUT
- Serial Number S/N



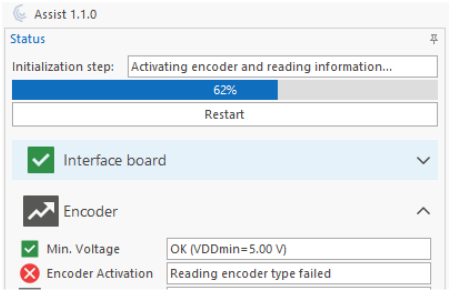
Troubleshooting

No valid device connected



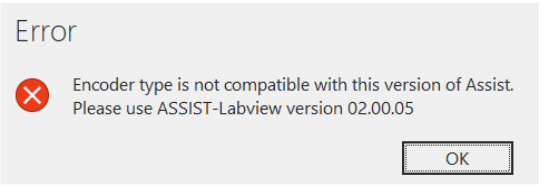
- Interface Board is not connected => Press OK, connect Interface Board with USB cable and press Restart (at the top of the Status window)
- Interface Board firmware is too old => Press OK, close ASSIST and load newest version of the Interface Board Firmware (in the ZIP-file with the ASSIST software downloaded from the POSIC website) according to the ASSIST Installation Manual.
- USB driver is not correct => Press OK, close ASSIST, but leave the Interface Board connected to the PC. Open the Device Manager on your PC (Open the Windows Start Menu and type “Device Manager”) and follow the instructions according to the ASSIST Installation Manual.

Reading Encoder Type failed in Status Window



- No encoder connected => Connect encoder and press Restart
- Malfunctioning encoder => Connect another encoder and press Restart
- One or more of the connections in the encoder-cable or encoder-connector are open-circuit => make sure that all electrical connections are correct and press Restart
- One or more of the encoder outputs A, B and/or I are short-circuited between each other or to VDD or to VSS => remove the short-circuit(s) and press Restart
- If a 5V-encoder is connected and VDDmin = 3.30 V => supply current during startup is too high. Make sure there are no other devices/components connected to the encoder supply voltage VDD. After correction, press Restart.

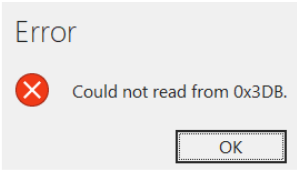
Encoder not compatible



- The ASSIST software is compatible to the encoders ID1102 and ID4501.
- The encoders IT3402, IT5602, AP3403, AP5603 and AP9200 are no compatible to this version of the ASSIST software. Please use ASSIST-LabView version 02.00.05 (downloadable from POSIC’s website) for these encoders.

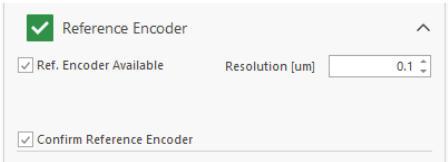
Could not read from 0x3DB

- Short circuit in encoder supply connection (VDD – VSS) => remove short-circuit (in encoder or in cable or in connector or on Interface Board) and press Restart



Measurement does not start

- If Ref. Encoder Available = off, the measurement is started as soon as the Start Live button has been pressed.
- If Ref. Encoder Available = on and the Start Live button has been pressed, the measurement is started as soon as the reference encoder is moving. As long as there are not A/B pulses from the reference encoder, the measurement will not start.



Glossary

ASSIST	Name of the software that runs on a PC and communicates via USB with the Interface Board
Booster voltage	The Interface Board receives a 5V USB supply-voltage. This voltage us stepped up with a booster to approximately 8.3 V in order to generate the different voltages required on the Interface Board. The Booster Voltage is measured during the startup of the ASSIST software and displayed in the Status Window under Interface Board. The value must be between 7.5 V and 9.0 V.
Codewheel	Disc or ring containing copper strips that is rotated on front of the encoder in order to measure the rotary position
Communication	Check if the communication between the Interface Board and the encoder is working correctly. The values shown between brackets are POSIC-internal traceability data.
DAQ / NORMAL	If Measurement Mode = NORMAL, the encoder is operated in normal mode with A quad B pulses, the measured position is purely incremental. If Measurement Mode = DAQ, the encoder is read out using a serial interface and the measured position represents the absolute position within one period of the scale/codewheel. The position is a 16-bit value ranging from 0 to 65’535.
Dump	The Memory Dump in the Status window under Encoder is a copy of the encoder’s complete OTP memory, stored in a .txt file. This file can be used by POSIC for failure analysis, traceability and other purposes.
ENC	LED on the Interface Board indicating that the encoder receives its supply voltage
Encoder Activation	Encoder Activation in the Status window under Encoder shows the supply current and voltage of the encoder in communication-modus. The current level is typically between 1 and 2 mA.
Encoder Type	The Encoder Type is automatically detected by the ASSIST software and displayed in the Status window under Encoder. The current version of the ASSIST version accepts encoder types ID1102, ID4501 and ID1302.
Fit	From the Non-Linearity measurement values an 8^{th} order Sinus-Fit is calculated, which is shown in the Non-Linearity-graph. This Fit is used to calculate the LookUp Table.
ID encoder	Incremental Dual-channel encoders ID1102 and ID4501
In-circuit programming	In-circuit programming of an encoder’s OTP memory while the encoder is connected to a controller or other electronic device
Index	ID encoders have an Index output signal that provides 1 Index-pulse per scale/codewheel period up to CC = 10. For CC > 10, the number of index-pulses per period is 2^{CC-10}.

Interface Board	Electronic board to which a POSIC encoder and a reference encoder can be connected and that is controlled by the ASSIST Software via USB.
IT encoder	Incremental Triple-channel encoders IT3402 and IT502
LED	Light Emitting Diode. The Interface Board contains red LEDs for the encoder signals, orange LEDs for the power supply and a yellow LED that lights up during OTP programming
LUT	LookUp Table to compensate periodic non-linearities caused by the encoder, by the scale/codewheel or by mounting tolerances
Memory Dump	The Memory Dump in the Status window under Encoder is a copy of the encoder's complete OTP memory, stored in a .txt file. This file can be used by POSIC for failure analysis, traceability and other purposes.
Min. Voltage	The Min Voltage is shown in the Status window under Encoder and corresponds to the minimum operating voltage that ASSIST detected. The minimum operating voltage should be 5 V for ID1102 encoders and may be 3.3 V or 5 V for ID4501 and ID1302 encoders.
NORMAL / DAQ	If Measurement Mode = NORMAL, the encoder is operated in normal mode with A quad B pulses, the measured position is purely incremental. If Measurement Mode = DAQ, the encoder is read out using a serial interface and the measured position represents the absolute position within one period of the scale/codewheel. The position is a 16-bit value ranging from 0 to 65'535.
OTP	One Time Programmable memory. This non-volatile or permanent memory in a POSIC encoder contains the configuration and calibration data and can be programmed only once.
OTP LUT	LUT stored in the encoder's OTP memory
Permanent memory	One Time Programmable (OTP) memory
PROG	Programming: yellow warning LED on the Interface Board that turns on during (irreversible) programming of the encoder's OTP memory
PWR	Power: LED indicating that the Interface Board is powered via the USB-cable
RAM	Random Access Memory: memory in the encoder that can be overwritten
RAM LUT	LUT stored in the encoder's RAM memory
RESET	Reset-button on the Interface Board. When activated, the microcontroller on the Interface Board and the USB-communication are reset.

Reset upon Index	Option in the measurement window. When Reset upon Index = On, the measured position will be reset to 0 upon each Index pulse. When Rest upon Index = Off, the measured position will not be reset upon Index pulses; the zero-position corresponds to the position at the start of the measurement. Reset upon Index is only selectable when Measurement Mode = NORMAL. In Measurement Mode = DAQ, the measured position is always reset upon each Index pulse, independent of the value of Reset upon Index.
S/N Serial Number	User-programmable serial number stored in the encoder's OTP memory. The serial number of three 16-bit values (0 – 65'535)
Scale	Linear scale or ruler containing copper strips that is linearly moved in front of the encoder in order to measure the linear position
Serial Number S/N	User-programmable serial number stored in the encoder's OTP memory. The serial number of three 16-bit values (0 – 65'535)
START/STOP	Start/stop button on the Interface Board that allows to start or stop operation of the encoder when it is operated without ASSIST
Supply	Check if the encoder's supply during normal operation are OK. Voltage should be 5 V or 3.3 V. Current depends on encoder settings and should be between 7 – 25 mA.
SYSTEM	LED on the Interface Board indicating that the microcontroller is active
Target	Object that moves in front of an encoder. For rotary applications, the target is a codewheel or a gear. For linear applications, the target is a linear scale.
USB	Universal Serial Bus. Connection between the PC (with ASSIST software) and the Interface Board. The Interface Board receives its power supply from the PC via the USB cable.

Interface Board connections

The POSIC Encoder is powered by the Interface Board (see image on page 1) via pin 1 of the 8-pin POSIC connector (Table 1). Do not apply an external supply voltage to the POSIC Encoder while it is connected to the Interface Board. Permanent damage may occur if the POSIC Encoder or the Interface Board are powered otherwise than via the USB-connection.

Tables 1 - 3 provide the pinouts of the encoder connectors and the green terminal block. The POSIC Encoder connections are in green, the Reference Encoder connections in red and the GND in blue (common GND between POSIC and Reference Encoders).

Table 1: Pinout of the 8-pin POSIC connector on the Interface Board

Pin nr.	Signal ID/IT enc.	Signal AP enc.	Comment
1	VDD	VDD	POSIC encoder supply voltage
2	GND	GND	Ground
3	A1	Clock1	Signal A or Clock1
4	B1	Data1	Signal B or Data1
5	I1	-	Signal I
6	A2	Clock2	Signal A2 or Clock2
7	B2	Data2	Signal B2 or Data2
8	I2	-	Signal I2

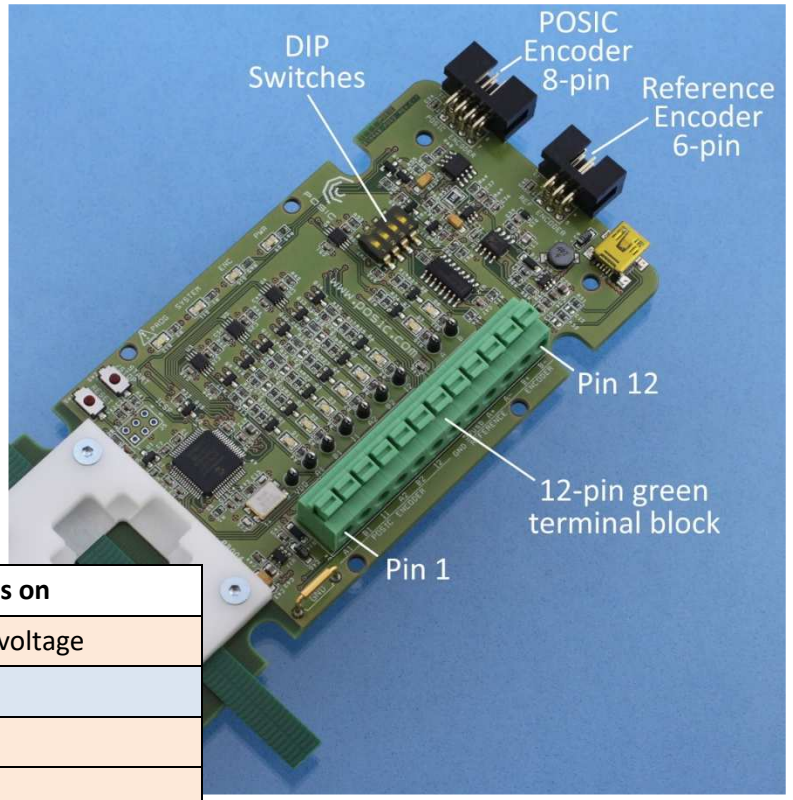


Table 2: Pinout of the 6-pin Reference Encoder connector on the Interface Board

Pin nr.	Signal	All DIP switches off (default)	All DIP switches on
1	5Vusb	Not connected	5V USB supply voltage
2	GND	Ground	
3	A+	Differential signal A, positive	Signal A
4	A-	Differential signal A, negative	Not connected
5	B+	Differential signal B, positive	Signal B
6	B-	Differential signal B, negative	Not connected

Table 3: Pinout of the 12-pin green terminal block on the Interface Board

Pin nr.	Signal	All DIP switches off (default)	DIP switch 1 = on and 2,3,4 = off	All DIP switches on
1	A1 / Clock1	POSIC encoder signal A		
2	B1 / Data1	POSIC encoder signal B		
3	I1	POSIC encoder signal I		
4	A2 / Clock2	POSIC encoder signal A2 (only for IT3402)		
5	B2 /Data2	POSIC encoder signal B2 (only for IT3402)		
6	I2	POSIC encoder signal I2 (only for IT3402)		
7	GND	Ground (common ground for POSIC and reference encoders)		
8	5Vusb	Not connected		Supply for Ref encoder
9	A+	Ref encoder diff signal A, positive	Ref encoder diff signal A, positive	Ref encoder signal A
10	A-	Ref encoder diff signal A, negative	Ref encoder diff signal A, negative	Not connected
11	B+	Ref encoder diff signal B, positive	Ref encoder diff signal B, positive	Ref encoder signal B
12	B-	Ref encoder diff signal B, negative	Ref encoder diff signal B, negative	Not connected

Important: **5Vusb (green terminal block pin 8) is NOT the supply for the POSIC encoder.** The POSIC-encoder supply VDD is not available on the green terminal block, it is only available on the POSIC encoder connector (pin 1 in Table 1)**.** 5Vusb may be used to supply the Reference encoder, see Tables 3 and 4.

The DIP switches on the Interface Board allow you to configure the supply of the reference encoder and the type of outputs of the reference encoder according to table 4.

Table 4: Configuration of the Reference Encoder by means of the DIP switches on the Interface Board

DIP Switches				Reference encoder supply	Reference encoder outputs
1	2	3	4		
off	off	off	off	External supply	RS422 differential
on	off	off	off	5V USB supply to Ref enc.	RS422 differential
off	on	on	on	External supply	5V TTL single-ended
on	on	on	on	5V USB supply to Ref enc.	5V TTL single-ended

When DIP switch 1 is **off**, the Interface Board does not provide a supply voltage to pin 1 of the Reference Encoder connector.
When DIP switch 1 is **on**, the Interface Board provides the 5V USB supply voltage to pin 1 of the Reference Encoder connector.

When DIP switches 2-4 are **off**, the RS422 line receiver on the Interface Board is enabled.
When DIP switches 2-4 are **on**, the RS422 line receiver on the Interface Board is disabled, its inputs are connected to the corresponding outputs, thus allowing single-ended 5V TTL Reference Encoder signals to pass to the microcontroller.

In-circuit programming

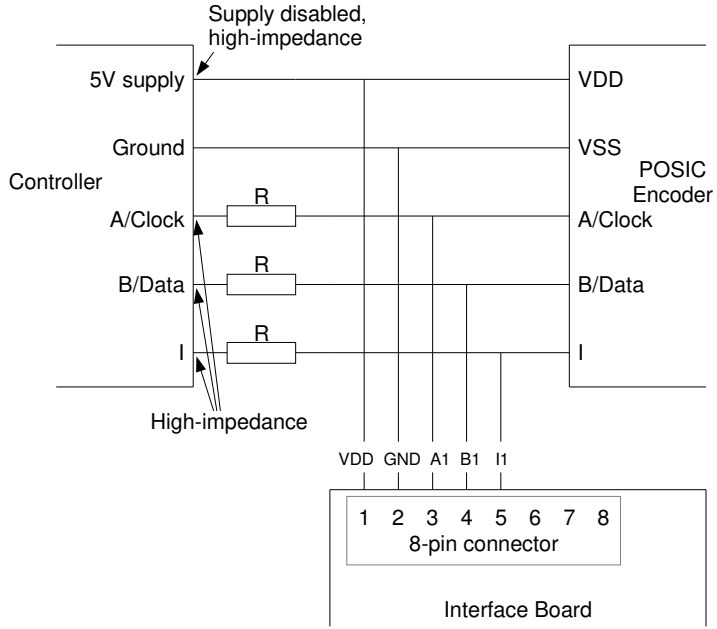
In-circuit programming is required when the linearization and/or the OTP-programming has to be carried out after the encoder has been permanently connected to a controller (e.g an SMD-encoder soldered on a PCB together with a microcontroller). During in-circuit programming, the Interface Board needs to control the encoder's supply voltage VDD and the pins A, B and I.

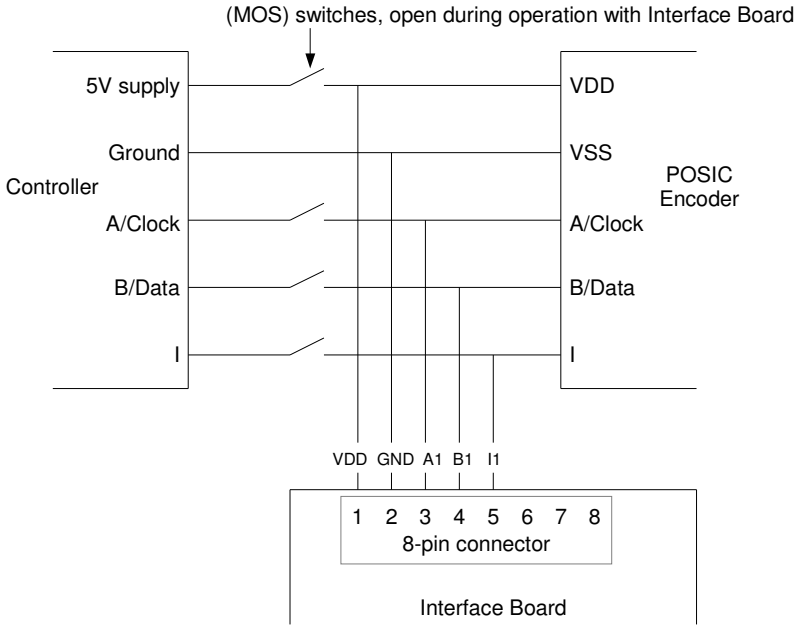
If it is possible to disable the 5V encoder-supply and to put the controller in/outputs (A, B, I) in high-impedance state, the schematic diagram below to the left shows the connections for in-circuit programming.

If it is not possible to disable the 5V encoder-supply or to put the controller in/outputs (A, B, I) in high-impedance state, the schematic diagram below to the right shows the connections for in-circuit programming.

During OTP-programming, the encoder supply voltage VDD and the voltage on A, B and I are increased to 6.5 V during a relatively short time (few seconds). Series resistors are recommended to protect the controller inputs during encoder-programming. Recommended value for the series resistor R = 100 – 1000 Ω.

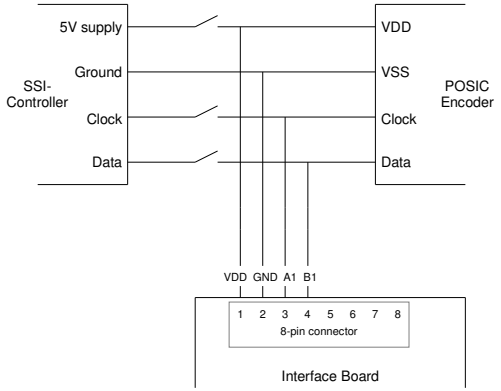
For in-circuit programming of 2-channel encoders (ID1102, ID4501), pins 3, 4 and 5 (A1, B1 and I1) of the 8-pin connector are used as shown in the schematic diagrams below. However, for 3-channel encoders (IT3402, IT5602), pins 3, 4, 5, 6, 7 and 8 (A1, B1, I1, A2, B2 and I2) of the 8-pin connector have to be used.



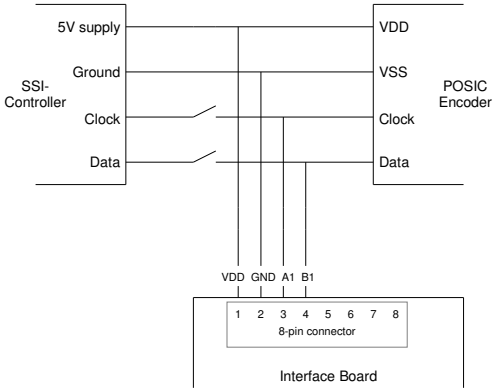


Connection to SSI or SPI controller

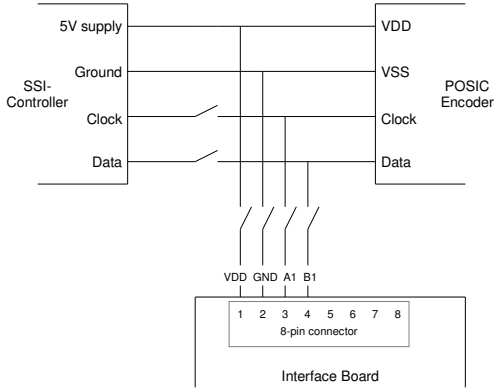
A POSIC encoder with SSI interface can be configured with the ASSIST software and then be operated (in closed-loop operation) with an SSI controller by following the sequence illustrated below.



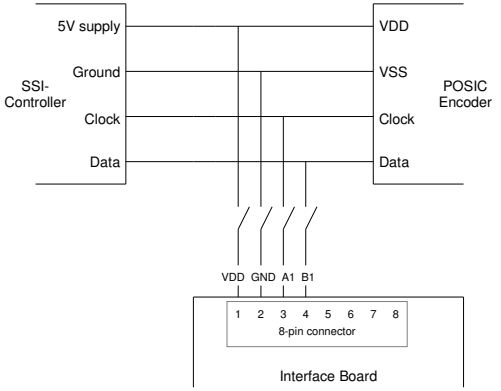
1) Connect the encoder to the Interface Board and configure the encoder with the ASSIST software



2) Connect the SSI controller's 5V supply to the encoder (the encoder is now supplied by the ASSIST Interface Board and the SSI controller in parallel).



3) Disconnect the Interface Board.



4) Connect Clock and Data from the SSI controller to the encoder.

For a 2-chip encoder (e.g. AP5603), this sequence should be applied for sensors 1 and 2 (with VDD1, VDD2, DATA1, DATA2, CLOCK1 and CLOCK2) in parallel.

For an AL-encoder with SPI interface, the I1/NCS1 connection on pin 5 should be handled the same way as the A1/CLOCK1 and B1/DATA1 on pins 3 and 4 respectively.